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Recurrent Neural Networks (RNNs) with Long Short-Term Memory units (LSTM) are widely used because they are expressive and are easy to train. Our interest lies in empirically evaluating the expressiveness and the learnability of LSTMs in the sequence-to-sequence

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regime by training them to evaluate short computer programs, a domain that has traditionally been seen as too complex for neural ...

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We found it difficult to train LSTMs to execute computer programs, so we used

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curriculum learning to simplify the learning problem. We design a curriculum procedure which outperforms both conventional training that uses no curriculum learning (baseline) as well as the naive curriculum learning of strategy of Bengio et al. (2009) (Section 4).

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PDF. Abstract: Graph neural networks (GNNs) have emerged as a powerful tool for learning software engineering tasks including code completion, bug finding, and program repair.

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A significant effort has been made to train neural networks that replicate algorithmic reasoning, but they often fail to learn the abstract concepts underlying these algorithms. This is evidenced by their inability to generalize to data distributions

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that are outside of their restricted training sets, namely larger inputs and unseen data. We study these generalization issues at the level of ...

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(Maddison & Tarlow, 2014) learned a language model on parse trees, and (Mou et al., 2014) predicted whether two programs are equivalent or not. Both of these approaches require parse trees, while we learn from a program charac-

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Human perception of
3D shapes goes
beyond reconstructing
them as a set of
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composition of
geometric primitives:
we also effortlessly
understand higher-
level shape structure

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such as the repetition and reflective symmetry of object parts. In contrast, recent advances in 3D shape sensing focus more on low-level geometry but less on these higher-level relationships. In this paper, we ...

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Learning to produce
efficient movement
behaviour for
humanoid robots from
scratch is a hard
problem, as has been

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illustrated by the
"Learning to run"
competition at NIPS
2017. The goal of this
competition was to
train a two-legged
model of a humanoid
body to run in a
simulated race course
with maximum speed.
All submissions took a
tabula rasa approach
to reinforcement
learning (RL) and

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We seek to efficiently
learn by leveraging
shared structure
between different
tasks and
environments. For
example, cooking is

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similar in different
kitchens, even though
the ingredients may
change location. In
principle, meta-
reinforcement
learning approaches
can exploit this
shared structure, but
in practice, they fail to
adapt to new
environments when
adaptation requires
targeted exploration

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~~[2008.02790] Explore~~

~~then Execute:~~

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abstract concepts underlying these algorithms. This is evidenced by their inability to generalize to data distributions that are outside of their restricted training sets, Page 2/8

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conventional To
curriculum learning
proved

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Learning to run a
Power Network
(L2RPN) with an
emphasis on the
challenging use of
topological flexibilities
and the safety
robustness

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requirement. The L2RPN competition which we will present and analyze here, takes some inspiration from the Learning to run [14] competition, whose goal was to learn a controller of a human body to walk and run ...

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...

Recently we proposed the Span Attribute Tagging (SAT) Model Du et al. (2019) to infer clinical entities (e.g., symptoms) and their properties (e.g., duration). It tackles the challenge of large label space and

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limited training data using a hierarchical two-stage approach that identifies the span of interest in a tagging step and assigns labels to the span in a classification step.

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